



University  
of Glasgow

# Network Programming in C

Networked Systems 3

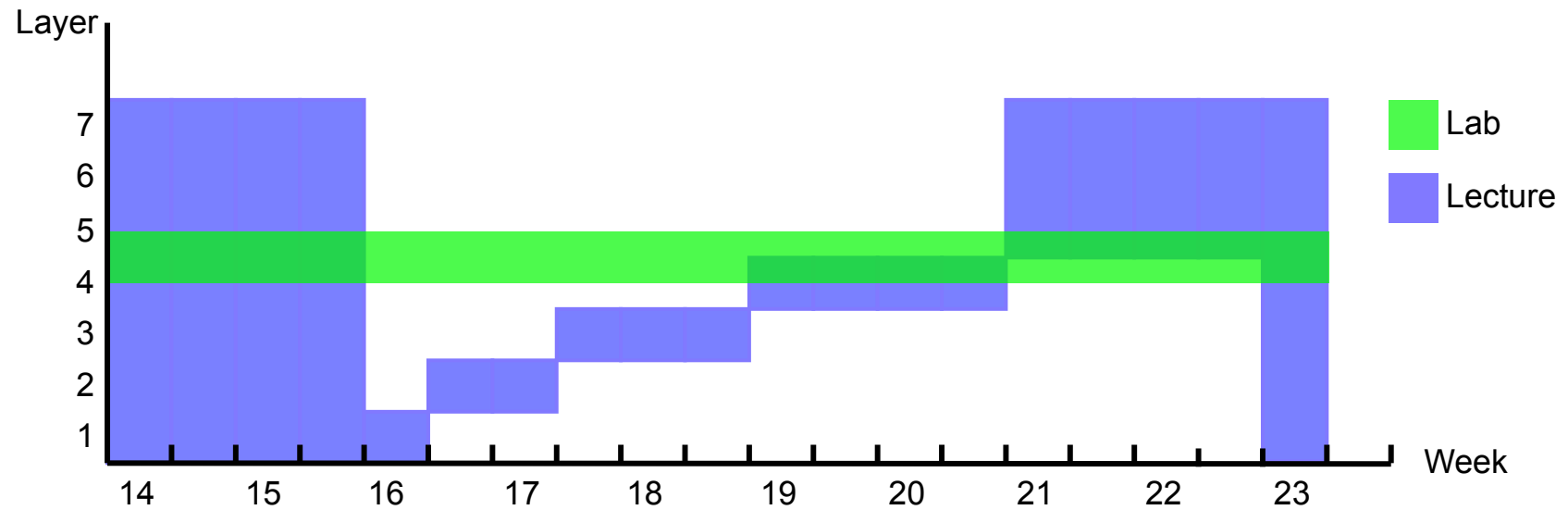
Laboratory Sessions and Problem Sets

# Lab Timetable, Aims, and Objectives

Teaching Week	Activity
14	Introduction
15	Warm-up exercise
16	Web client
17	
18	
19	Web server
20	
21	
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23	-

- Aims and objectives
  - To demonstrate how the world-wide web works, at a protocol level
  - To teach concurrent network programming in C

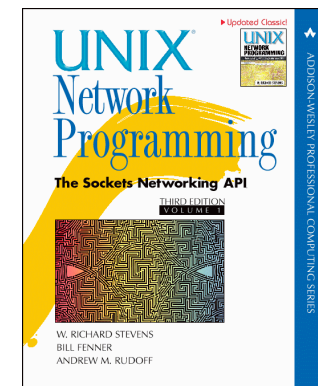
# Relation Between Labs and Lectures



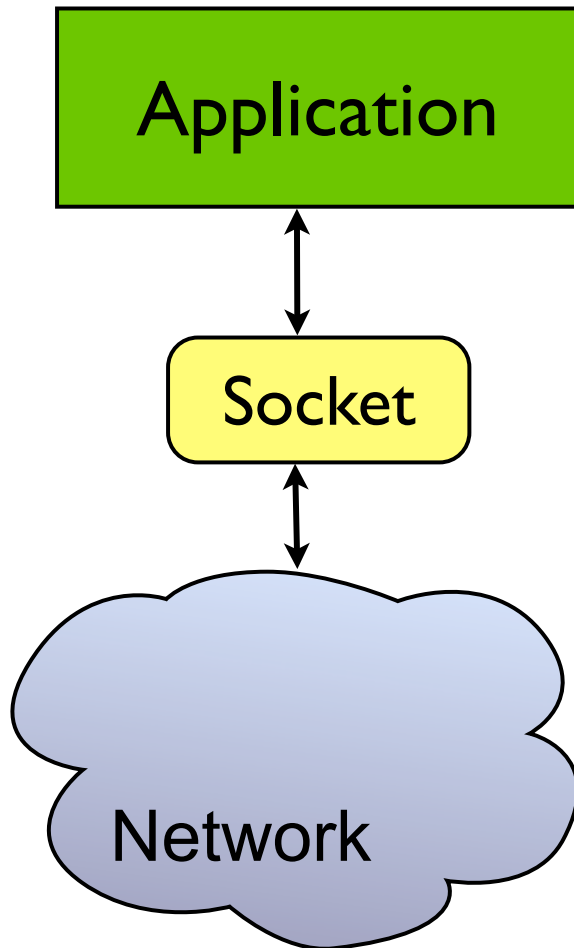
# Network Programming in C: The Berkeley Sockets API

# The Berkeley Sockets API

- Widely used low-level C networking API
- First introduced in 4.3BSD Unix
  - Now available on most platforms: Linux, MacOS X, Windows, FreeBSD, Solaris, etc.
  - Largely compatible cross-platform
- Recommended reading:
  - Stevens, Fenner, and Rudoff, “Unix Network Programming volume 1: The Sockets Networking API”, 3rd Edition, Addison-Wesley, 2003.



# Concepts

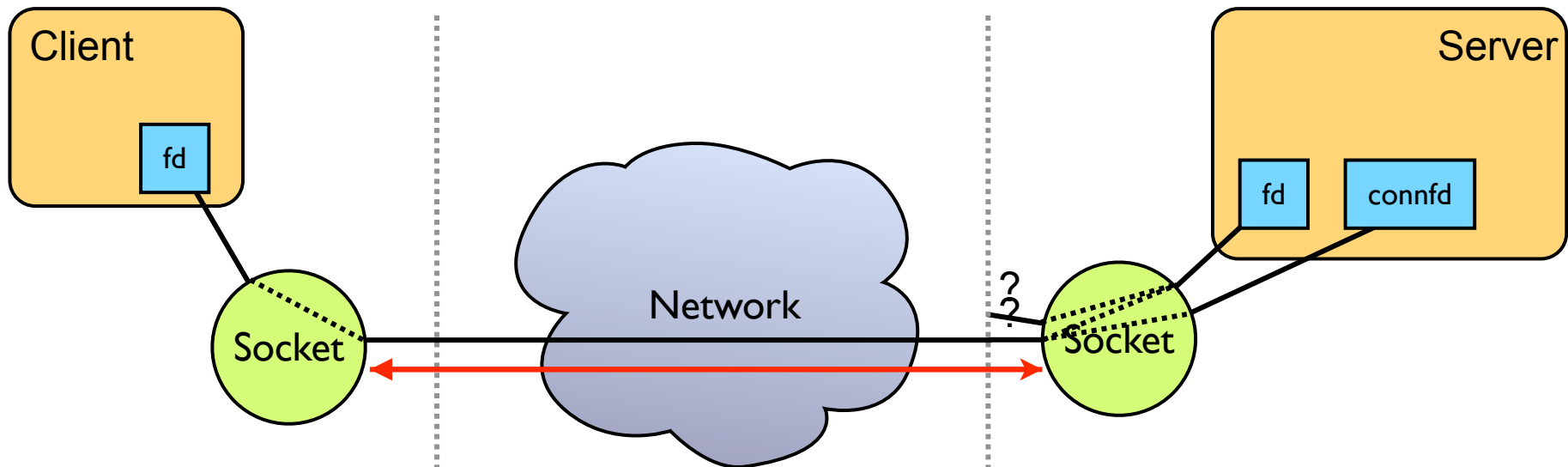


- Sockets provide a standard interface between network and application
- Two types of socket:
  - Stream – provides a virtual circuit service
  - Datagram – delivers individual packets
- Independent of network type:
  - Commonly used with TCP/IP and UDP/IP, but not specific to the Internet protocols
  - Only discuss TCP/IP sockets today

# What is a TCP/IP Connection?

- A reliable byte-stream connection between two computers
  - Most commonly used in a client-server fashion:
    - The server listens on a well-known *port*
      - The *port* is a 16-bit number used to distinguish servers
      - E.g. web server listens on port 80, email server on port 25
    - The client connects to that port
  - Once connection is established, either side can write data into the connection, where it becomes available for the other side to read
- The Sockets API represents the connection using a *file descriptor*

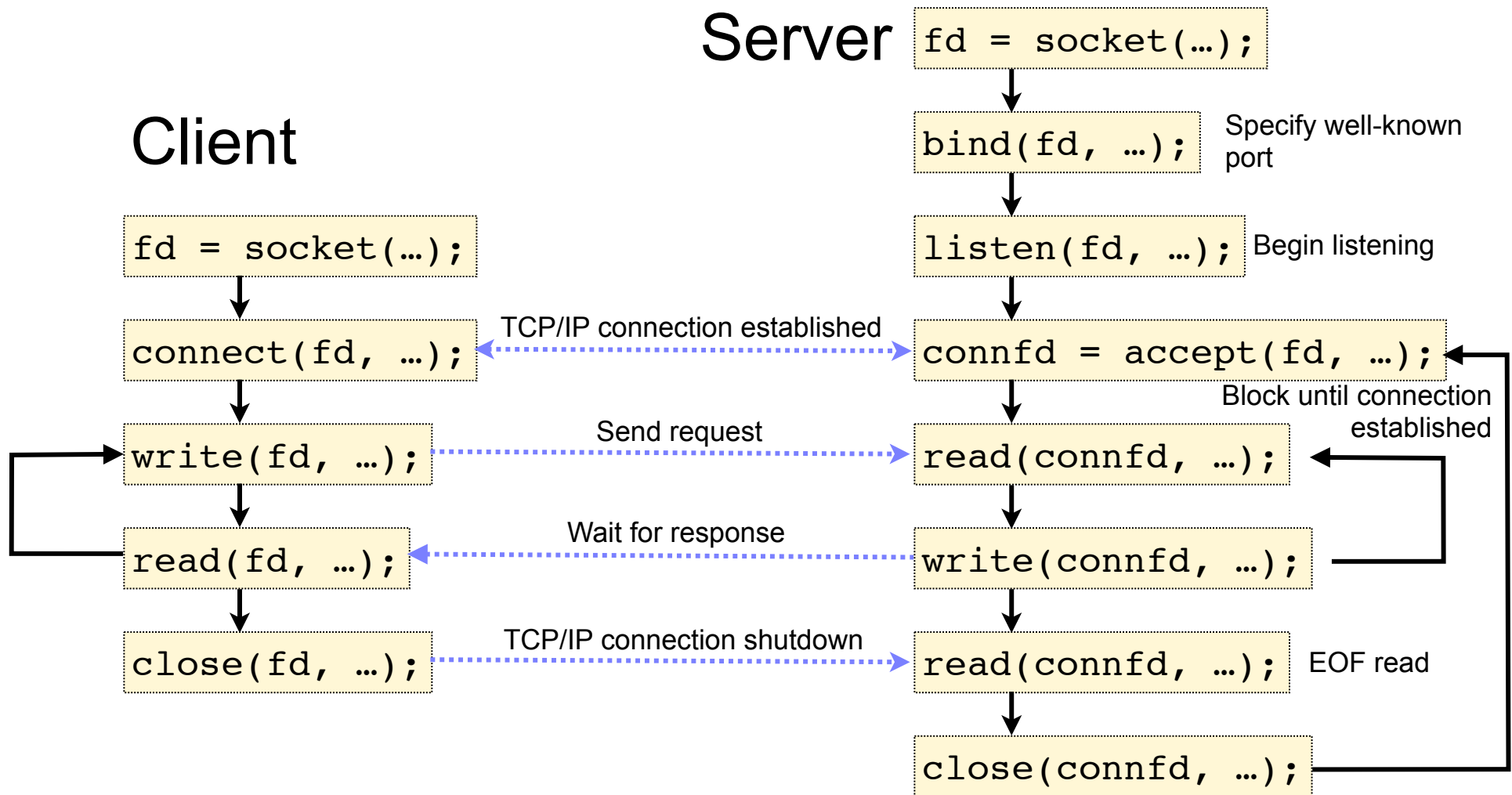
# TCP/IP Connection



```
int fd = socket(...)  
  
connect(fd, ..., ...)  
write(fd, data, datalen)  
read(fd, buffer, buflen)  
close(fd)
```

```
int fd = socket(...)  
bind(fd, ..., ...)  
listen(fd, ...)  
connfd = accept(fd, ...) ←  
read(connfd, buffer, buflen)  
write(connfd, data, datalen)  
close(connfd) ———
```

# TCP/IP Connection



# Creating a socket

```
#include <sys/types.h>
#include <sys/socket.h>
```

```
int fd;
...
fd = socket(family, type, protocol);
if (fd == -1) {
    // Error: unable to create socket
    ...
}
...
```

AF\_INET for IPv4  
AF\_INET6 for IPv6

SOCK\_STREAM for TCP  
SOCK\_DGRAM for UDP

0 (not used for Internet sockets)

Create an unbound socket, not connected to network;  
can be used as either a client or a server

# Handling Errors

Socket functions return `-1` and set the global variable `errno` on failure

```
fd = socket(family, type, protocol);
if (fd == -1) {
    switch (errno) {
        case EPROTONOSUPPORT :
            // Protocol not supported
            ...
        case EACCESS:
            // Permission denied
            ...
        case ...
        default:
            // Other error...
            ...
    }
}
```

The Unix man pages list possible errors that can occur for each function

E.g. do “`man 2 socket`” in a terminal, and read the **ERRORS** section

# Binding a Server Socket

- Bind a socket to a port on a network interface
  - Needed to run servers on a well-known port - with *addr* specified as `INADDR_ANY`
  - Not generally used on clients, since typically don't care which port used

```
#include <sys/types.h>
#include <sys/socket.h>
...
if (bind(fd, addr, addrlen) == -1) {
    // Error: unable to bind
    ...
}
...
```

# Listening for Connections

```
#include <sys/types.h>
#include <sys/socket.h>
```

```
if (listen(fd, backlog) == -1) {
    // Error
    ...
}
...
```

Tell the socket to listen for new connections

The *backlog* is the maximum number of connections the socket will queue up, each waiting to be `accept ( )`'ed

# Connecting to a Server

```
#include <sys/types.h>
#include <sys/socket.h>
```

```
if (connect(fd, addr, addrlen) == -1) {
    // Error: unable to open connection
    ...
}
...
```

Pointer to a struct sockaddr

Size of the struct in bytes

Tries to open a connection to the server  
Times out after 75 seconds if no response

# Specifying Addresses & Ports

- Must specify the address and port when calling `bind()` or `connect()`
  - The address can be either IPv4 or IPv6
  - Could be modelled in C as a union, but the designers of the sockets API chose to use a number of structs, and abuse casting instead

# struct sockaddr

- Addresses specified via `struct sockaddr`
  - Has a data field big enough to hold the largest address of any family
  - Plus `sa_len` and `sa_family` to specify the length and type of the address
  - Treats the address as an opaque binary string

```
struct sockaddr {  
    uint8_t      sa_len;  
    sa_family_t  sa_family;  
    char         sa_data[22];  
};
```

# struct sockaddr\_in

- Two variations exist for IPv4 and IPv6 addresses
  - Use struct sockaddr\_in to hold an IPv4 address
  - Has the same size and memory layout as struct sockaddr, but interprets the bits differently to give structure to the address

```
struct in_addr {
    in_addr_t    s_addr;
};

struct sockaddr_in {
    uint8_t      sin_len;
    sa_family_t  sin_family;
    in_port_t    sin_port;
    struct in_addr sin_addr;
    char         sin_pad[16];
};
```

# struct sockaddr\_in6

- Two variations exist for IPv4 and IPv6 addresses
  - Use struct sockaddr\_in6 to hold an IPv6 address
  - Has the same size and memory layout as struct sockaddr, but interprets the bits differently to give structure to the address

```
struct in6_addr {
    uint8_t      s6_addr[16];
};

struct sockaddr_in6 {
    uint8_t      sin6_len;
    sa_family_t  sin6_family;
    in_port_t    sin6_port;
    uint32_t     sin6_flowinfo;
    struct in6_addr sin6_addr;
};
```

# Working with Addresses

- Work with either `struct sockaddr_in` or `struct sockaddr_in6`
- Cast it to a `struct sockaddr` before calling the socket routines

```
struct sockaddr_in  addr;
...
// Fill in addr here
...
if (bind(fd, (struct sockaddr *) &addr, sizeof(addr)) == -1) {
    ...
}
```

# Creating an Address: Manually (Client)

```
#include <sys/types.h>
#include <sys/socket.h>
#include <netinet/in.h>
#include <arpa/inet.h>
```

`inet_pton()` to convert address  
`htons()` to convert port

```
struct sockaddr_in  addr;
...
inet_pton(AF_INET, "130.209.240.1", &addr.sin_addr);
addr.sin_family = AF_INET;
addr.sin_port   = htons(80);

if (connect(fd, (struct sockaddr *)&addr, sizeof(addr)) == -1) {
    ...
}
```

# Creating an Address: Manually (Server)

```
#include <sys/types.h>
#include <sys/socket.h>
#include <netinet/in.h>
#include <arpa/inet.h>
```

Usually specify `INADDR_ANY`  
`htons ( )` to convert port

```
struct sockaddr_in  addr;
...
addr.sin_addr.s_addr = INADDR_ANY;
addr.sin_family      = AF_INET;
addr.sin_port        = htons(80);

if (bind(fd, (struct sockaddr *)&addr, sizeof(addr)) == -1) {
    ...
}
```

# Creating an Address: DNS

- Prefer using DNS names to raw IP addresses
  - Use `getaddrinfo()` to look-up name in DNS
  - Returns a linked list of `struct addrinfo` values, representing addresses of the host

```
struct addrinfo {
    int             ai_flags;        // input flags
    int             ai_family;      // AF_INET, AF_INET6, ...
    int             ai_socktype;    // IPPROTO_TCP, IPPROTO_UDP
    int             ai_protocol;    // SOCK_STREAM, SOCK_DGRAM, ...
    socklen_t       ai_addrlen;     // length of socket-address
    struct sockaddr *ai_addr;       // socket-address for socket
    char            *ai_canonname;  // canonical name of host
    struct addrinfo *ai_next;       // pointer to next in list
};
```

# Connecting via a DNS Query

```
struct addrinfo  hints, *ai, *ai0;

memset(&hints, 0, sizeof(hints));
hints.ai_family   = PF_UNSPEC;
hints.ai_socktype = SOCK_STREAM;
if ((i = getaddrinfo("www.google.com", "80", &hints, &ai0)) != 0) {
    printf("Unable to look up IP address: %s", gai_strerror(i));
    ...
}

for (ai = ai0; ai != NULL; ai = ai->ai_next) {
    fd = socket(ai->ai_family, ai->ai_socktype, ai->ai_protocol);
    if (fd == -1) {
        perror("Unable to create socket");
        continue;
    }

    if (connect(fd, ai->ai_addr, ai->ai_addrlen) == -1) {
        perror("Unable to connect");
        close(fd);
        continue;
    }
    ...
}
```

# Accepting Connections

```
#include <sys/types.h>
#include <sys/socket.h>
```

```
int          connfd;
struct sockaddr_in cliaddr;
socklen_t    cliaddrlen = sizeof(cliaddr);
...
connfd = accept(fd, (struct sockaddr *) &cliaddr, &cliaddrlen);
if (connfd == -1) {
    // Error
    ...
}
...
```

Accepts a connection, returns *new* file descriptor for the connection (`connfd`) and client address (`cliaddr`)

# Accepting Connections

- A TCP/IP server may have multiple connections outstanding
  - Can `accept ( )` connections one at a time, handling each request in series
  - Can `accept ( )` connections and start a new thread for each, allowing it to process several in parallel
- Each call to `accept ( )` returns a new file descriptor

# Reading and Writing Data

```
#define BUFLLEN 1500
...
ssize_t i;
ssize_t rcount;
char    buf[BUFLLEN];
...
rcount = read(fd, buf, BUFLLEN);
if (rcount == -1) {
    // Error has occurred
    ...
}
...
for (i = 0; i < rcount; i++) {
    printf("%c", buf[i]);
}
```

Read up to BUFLLEN bytes of data from connection; blocks until data available

Returns actual number of bytes read, or -1 on error

Data is *not* null terminated

# Reading and Writing Data

```
char data[] = "Hello, world!";  
int  datalen = strlen(data);  
...  
if (write(fd, data, datalen) == -1) {  
    // Error has occurred  
    ...  
}  
...
```

Send data on a TCP/IP connection; blocks until all data can be written

Returns actual number of bytes written, or -1 on error

# Reading and Writing Data

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>

int main()
{
    char    x[] = "Hello, world!";
    char    *y    = malloc(14);

    sprintf(y, "Hello, world!");

    printf("x = %s\n", x);
    printf("y = %s\n", y);

    printf("sizeof(x) = %d\n", sizeof(x));
    printf("sizeof(y) = %d\n", sizeof(y));

    printf("strlen(x) = %d\n", strlen(x));
    printf("strlen(y) = %d\n", strlen(y));

    return 0;
}
```

What gets printed?

Why?

# Closing a Socket

```
#include <unistd.h>
```

```
close(fd);
```

## Close and destroy a socket

Close the file descriptor for each connection, then the file descriptor for the underlying socket

# Programming Exercises

# Assessment

- Laboratory work is assessed, total weighting 20%

Exercise	Date set	Date due*	Weighting
Warm-up	13 January	26 January, 12:00pm	4%
Web client	27 January	16 February, 12:00pm	6%
Web server	17 February	12 March, 12:00pm	10%

\* Note: these are hard deadlines; late submissions will receive a mark of zero unless accompanied by a valid special circumstances form.

- All students are required to attend Wednesday labs

# Warm-up Exercise

- Write two programs in C: `hello_client` and `hello_server`
  - The server listens for, and accepts, a single TCP connection; it reads all the data it can from that connection, and prints it to the screen; then it closes the connection
  - The client connects to the server, sends the string “Hello, world!”, then closes the connection
- Details on the handout...

Questions?